

NPM800R-NPM800RE

RETROFITTING - Motor Protection Relay



NPM800R (R2 case) and NPM800RE (R3 case) are dedicated to the refurbishment of 7000 series (R2 and R3 cases) of CEE relays providing the protection of medium voltage and high power motor for low voltage. These numerical and multi-function relays analyze the currents absorbed by the motor during the starting, reacceleration and normal operation phases.

NP800R relays provide monitoring, measurement and recording of the electrical quantities of the network. The relays can be set locally, using either the keypad and display or the RS232 port, or remotely using the RS485 port.

Two mountings are available, Flush Rear Connection (**EDPAR**) or Projecting Rear Connection (**SDPAR**).

Setting, reading, measurement and recording are all available locally or remotely.



- Minimises retrofitting man-hours
- Maximises preservation of existing installation
- Simplifies and reduces re-commissioning time
- Minimises retrofitting costs

NPM800RE / NPM800R - EDPAR

Protection functions

- Thermal start authorisation [5]
- Thermal overload [49]
- Too long start [48]
- Locked rotor [51LR]
- Phase to phase short-circuit [50]
- Limitation of number of starts [66]
- Unbalance, Reversal and Loss of Phase [46]
- Earth fault [51N]
- Minimum of Load - Unpriming [37I]

Additional functions

- Latching of the output contacts [86]
- Trip circuit supervision of the breaker [74TC]
- Breaker failure [50BF] [50N_BF]
- Load shedding by external input and high speed restarting
- Load shedding - Load Restoration, remote control

OUR TRADEMARKS



GENERAL CHARACTERISTICS

Auxiliary Supply <ul style="list-style-type: none"> • Auxiliary supply ranges • Typical burden • Memory backup 	19 to 70 – 85 to 255 / Vdc or Vac 50 or 60 Hz 6 W (DC), 6 VA (AC) 72 hours
Analogue inputs <ul style="list-style-type: none"> • Phase CT 	In 1 or 5 A burden at In < 0.2 VA Continuous rating 3 In, short duration withstand 80 In / 1s CT setting: primary value from 1 A to 10 kA measurement from 0.05 to 24 In display of primary current from 0 to 65 kA
<ul style="list-style-type: none"> • Earth current CT 	In ₀ 1 or 5 A burden at In ₀ < 0.5 VA Continuous rating 1 In ₀ , short duration withstand 40 In ₀ / 1s measurement from 0.005 to 2.4 In ₀ display of primary current from 0 to 6.5 kA
<ul style="list-style-type: none"> • Recommended CTs 	5VA 5P15
<ul style="list-style-type: none"> • Earth current from Ring CT 100/1 or Ring CT 1500/1 and BA800 	measurement from 0.1 to 48 A primary
<ul style="list-style-type: none"> • Frequency (50Hz or 60Hz) 	measurement: 45 to 55 Hz or 55 to 65 Hz
Digital inputs (4 for NPM800R ; 8 for NPM800RE) <ul style="list-style-type: none"> • Polarizing voltage • Level 0 • Level 1 • Operating of the input by level 1 or 0 • Burden 	20 to 70 Vdc for 19 to 70 V auxiliary supply range 37 to 140 Vdc for 85 to 255 V auxiliary supply range < 10 Vdc range 19 to 70 V – < 33 Vdc range 85 to 255 V > 20 Vdc range 19 to 70 V – > 37 Vdc range 85 to 255 V programmable < 15 mA
Output Relays (3* for NPM800R + 1 WD ; 7 for NPM800RE + 1 WD) <ul style="list-style-type: none"> • Relays A*, B*, E, F: (signalling, Shunt Opening Release) 	double contact NO, permanent current 8 A closing capacity 12 A / 4 s short circuit current withstand 100 A / 30 ms breaking capacity DC with L/R = 40 ms: 50W breaking capacity AC with cos φ = 0.4: 1,250 VA
<ul style="list-style-type: none"> • Relays C*, D, G & WD: (control, WD: Watchdog) (C, D, G: programmable for CB Shunt Opening Release or Under Voltage Release) 	changeover contact, permanent current 10 A closing capacity 15 A / 4 s short circuit current withstand 250 A / 30 ms breaking capacity DC with L/R = 40 ms: 50W breaking capacity AC with cos φ = 0.4: 1,250 VA
<ul style="list-style-type: none"> • Relays pulse, except WD 	adjustable from 100 to 500 ms
<ul style="list-style-type: none"> • Assignment of name to the output maximum of 16 characters 	by the setting software capital letters or digits
Thermal start authorisation [5] <ul style="list-style-type: none"> • Thermal start authorisation 	40 to 100% θ thermal, class 5
Thermal overload [49] <ul style="list-style-type: none"> • Tripping curves • Heating-time constant C_{TE} • Cooling time constant • Negative sequence factor • Factor of start F_D • Thermal trip threshold I_{ref} • Thermal alarm threshold 	IEC 60255-8 4 to 180 min, class 5 1 to 6.0 C _{TE'} in step of 0.1 0 to 9 50 to 100% C _{TE} 40 to 130 % In, class 5 50 to 100 % θ thermal, class 5

GENERAL CHARACTERISTICS

<p>Too long start [48] and locked rotor [51LR]</p> <ul style="list-style-type: none"> • Operating range • Thresholds accuracy • Too long start time delay [48] • Accuracy of the time delays [48] • Locked rotor time delay [51LR] • Accuracy of the time delays [51LR] 	<p>1 to 10 I_{ref} $\pm 5\%$ 2 to 200 s $\pm 5\%$ 0.2 to 20 s $\pm 5\%$</p>
<p>Phase to phase short-circuit [50]</p> <ul style="list-style-type: none"> • Operating range $I >>$ • Phase threshold accuracy • Reset percentage on the operating level • Instantaneous operating time • Definite time delay • Accuracy of the time delay 	<p>3 à 12 I_n 3% 95% 60 ms including trip relay for $I \geq 2 I_s$ 40 ms to 3 s $\pm 2\%$ or 20 ms</p>
<p>Limitation of number of starts [66]</p> <ul style="list-style-type: none"> • Number of authorized starts • Reference period • Blocking period • Accuracy of the time delays 	<p>from 1 to 4 15 to 60 min 15 to 60 min $\pm 5\%$</p>
<p>Unbalance, Reversal and Loss of Phase [46]</p> <ul style="list-style-type: none"> • Operating range $I2 >$ • Inverse curves • Reset percentage on the operating level 	<p>20 to 80% I_n, accuracy $\pm 5\%$ 1 to 10 s (for $I_{neg} = 100\% I_{neg}/I_n$), accuracy $\pm 5\%$ 94 %, accuracy $\pm 1\%$</p>
<p>Earth fault [51N]</p> <ul style="list-style-type: none"> • Operating range $I0 >$ • Thresholds accuracy • Reset percentage on the operating level • Instantaneous operating time • Definite time delay • Accuracy of the time delay • Blocking during starting period 	<p>0.03 to 2.4 I_{n0} / CT - 0.6 to 48 A / ring CT 1% typical, 2% max from 0.05 to 2.4 I_{n0} / CT 3% typical, 5% max from 0.03 to 0.05 I_{n0} / CT 5% from 0.6 to 48 A / ring CT 95% 60 ms including trip for $I \geq 2 I_s$ 40 ms to 3 s $\pm 5\%$ or 20 ms programmable: active / inactive</p>
<p>Minimum of Load - Unpriming [37I]</p> <ul style="list-style-type: none"> • Operating range $I <$ • Operating time delay • Accuracy of the time delay • Reset percentage on the operating level 	<p>0.1 to 2.4 I_n, accuracy $\pm 5\%$ 0.05 to 120 s $\pm 5\%$ or 20 ms 106 %, accuracy $\pm 1\%$</p>
<p>Trip circuit supervision and breaker failure [74TC] [50BF] [50N_BF]</p> <ul style="list-style-type: none"> • Trip circuit supervision [74TC] • Operating time (in faulty condition) • Failure threshold [50BF] • Failure threshold [50N_BF] • Breaker failure time delay 	<p>requires one or two digital inputs (see application guide) 500 ms fixed for [74TC] function 5% to 30 % I_n, step of 1 I_n 0.5% to 3% I_{n0}, step of 0.1 I_{n0} 60 to 1,000 ms, step of 10 ms</p>
<p>Latching of the output contacts [86]</p> <ul style="list-style-type: none"> • Manual reset for output relays • Reset 	<p>A, B, C and according to version D, E, F, G (programmable assignment) digital input, digital communication or local MMI</p>

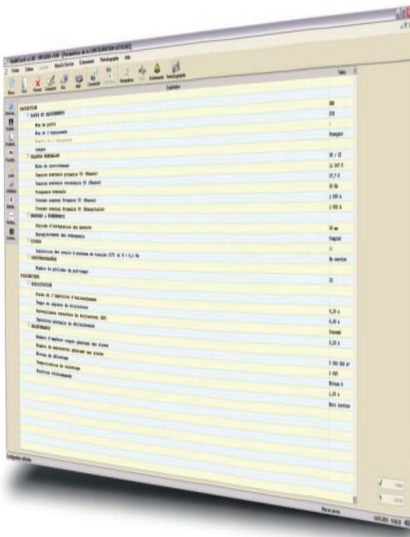
GENERAL CHARACTERISTICS

<p>Digital inputs assignment</p> <ul style="list-style-type: none"> • By setting software • Setting table selection • Disturbance recording order • Logical selectivity • Interlock o/o • Interlock c/o • Control mode • Closing mode • Reset [86] function • Trip circuit supervision • CB trip external order • Input – output programmable functions 	<p>set 1 – set 2</p> <p>dedicated to remote control, local / remote</p> <p>acknowledgment of the selected output(s) [74TC] function function [74TC] blocked if external trip order</p>
<p>User programmable functions (digital inputs – digital outputs)</p> <ul style="list-style-type: none"> • Status of the function • Tripping mode or report • Operating and release time delays • Assignment of name to the function, maximum of 14 characters • Assignment of one or more output relays (alarm or trip) 	<p>in or out of service, by local MMI or by the setting software report: for time stamping and event recorder tripping mode: 40 ms to 300 s by the setting software by local MMI or by the setting software A, B, C and according to version D, E, F, G</p>
<p>Counters</p> <ul style="list-style-type: none"> • Cumulative breaking current • Operation number of circuit breaker • Working time of the motor since its last energizing • Working time of the motor since its commissioning 	<p>maximum $64 \cdot 10^6$ kA² (phase 1 and 3) 0 à 10,000 0 minute to 65,535 hours 0 to 65,535 hours</p>
<p>Load shedding by external input and high speed restarting</p> <ul style="list-style-type: none"> • Load shedding time delay • Reacceleration during a time corresponding to a starting [48] 	<p>60 ms to 120 s, accuracy $\pm 5\%$ If the external order disappears before the end of the time delay</p>
<p>Load shedding – Load Restoration, remote control</p> <ul style="list-style-type: none"> • Load shedding level • Time delay before reclosing • Reclosing pulse • Output relays assigned 	<p>1 to 6 1 to 120 s, $\pm 2\%$ 100 to 500 ms (remote control) programmable by local MMI or by setting software A, B, C and according to version D, E, F, G</p>
<p>Digital outputs assignment</p> <ul style="list-style-type: none"> • By local MMI or by setting software 	
<p>Signalling LEDs assignment</p> <ul style="list-style-type: none"> • By setting software 	
<p>Man Machine Interface</p> <ul style="list-style-type: none"> • Relay display Language • Configuration and operating software Language 	<p>2 lines of 16 characters French, English, Spanish, Italian Windows® 2000, XP, Vista and 7 compatible French, English, Spanish, Italian</p>
<p>MODBUS® Communication</p> <ul style="list-style-type: none"> • Transmission • Interface • Transmission speed 	<p>asynchronous series, 2 wires RS485 300 to 115,200 bauds</p>

GENERAL CHARACTERISTICS

<p>Disturbance recording</p> <ul style="list-style-type: none"> • Number of recordings • Total duration • Pre fault time 	<p>4 52 periods per recording adjustable from 0 to 52 cycles</p>
<p>Presentation</p> <ul style="list-style-type: none"> • Height • Width • Brackets 19" rack mounting 	<p>4U case R2 or R3 according to version see diagram 9954 (7000 series rack definition table)</p>
<p>Case (see drawing D40037)</p> <ul style="list-style-type: none"> • EDPAR H, W, D (case & base) H, W (front face dimensions) • SDPAR H, W, D (case & base) H, W (front face dimensions) • Weight 	<p>NPM800R: 172 x 83 x 222 mm NPM800RE: 172 x 125 x 222 mm NPM800R: 217 x 98 mm NPM800RE: 217 x 140 mm NPM800R: 172 x 83 x 227 mm NPM800RE: 172 x 125 x 227 mm NPM800R: 172 x 83 mm NPM800RE: 172 x 125 mm NPM800R: 3.5 kg NPM800RE: 4.5 kg</p>
<p>Connection - codification</p> <ul style="list-style-type: none"> • NPM800R • NPM800RE • Ring CT • BA800 	<p>see diagram S39966 see diagram S39971 see diagram 142941 see diagram 38766</p>

SMARTsoft, integrated software for the Industry, Railway and Transmission ranges, helps the User get the best from NP800R series relays



- User friendly
- Diagnosis
- Fault analysis
- Maintenance tools

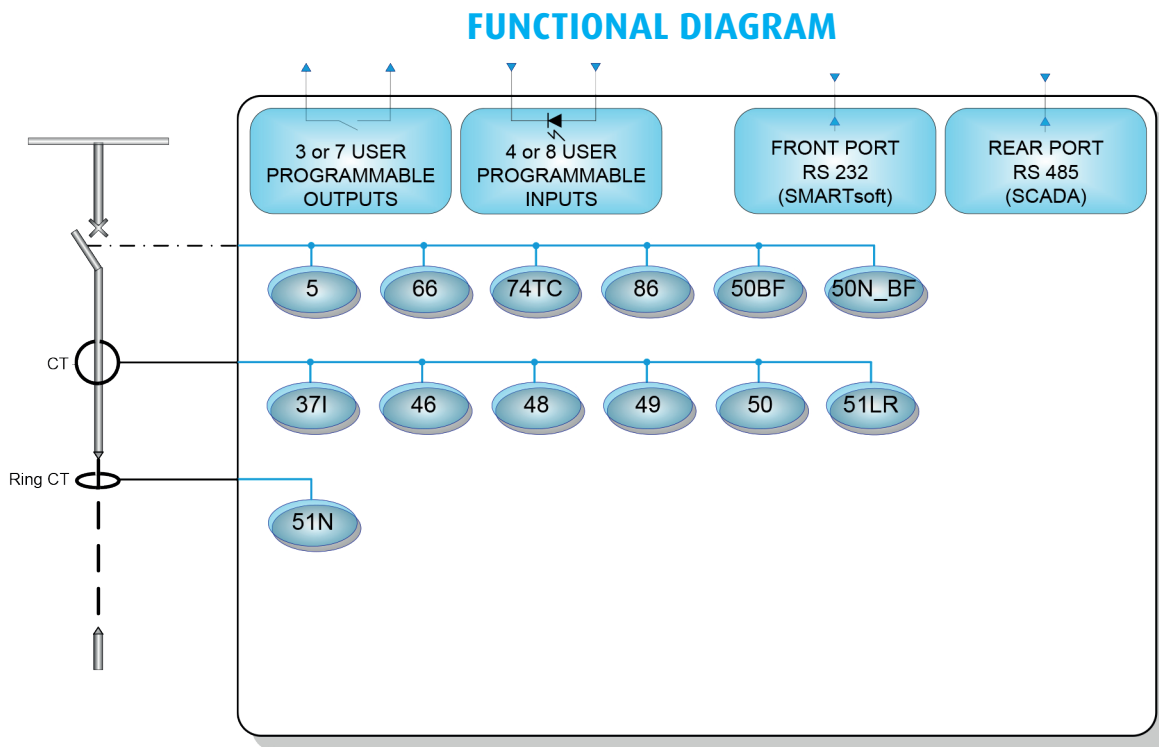
FUNCTIONALITIES

- 2 ranges of auxiliary supply
- Storage of the lack and the restoration of the auxiliary voltage (time stamped events)
- Configuration and parameter setting by local MMI or off-line / on-line PC
- Measurement of electrical quantities: Display expressed in primary values Instantaneous, integrated and maximum values of phase and earth currents
- Instantaneous alarm threshold
- Definite time tripping
- Dependent time tripping according to inverse/very inverse/extremely inverse IEC 60255-3 curves
- Tripping according to RI curve (electromechanical)
- Tripping according to moderately inverse/very inverse/extremely inverse ANSI /IEEE curves
- Logical selectivity on the three phase thresholds and the two earth thresholds
- Thermal image according to IEC 60255-8
- Cable (by phase) and transformer (3 phase)
- 2 setting groups, locally or remotely selectable
- CB Monitoring: interlocks discrepancy, local or remote control of closing / tripping
- Circuit breaker maintenance: counters of operation number and cut-off amperes² per phase, alarm and threshold
- Monitoring of breaker failure by checking the disappearance of current after opening
- Remote control by communication channel: tripping or closing, load shedding with priority levels and load restoration
- Setting software compatible with Windows® 2000, XP, Vista and 7
- User interface with access to all protection functions
- Time stamping of internal events with 10ms resolution
- Time stamping of digital inputs with 10ms resolution
- Event recording: 250 locally recorded events, 200 saved in case of loss of auxiliary supply

- Recording of measurements and current setting group
- Local / remote events acknowledgment
- Disturbance recording according to Comtrade® format: storage of 4 recordings of 52 periods
- Disturbance recording initiated by digital input, setting software or communication channel
- Closing function: adjustment of phase, earth, negative sequence current thresholds by external input
- Remote setting and reading of measurements, counters, alarms and parameter settings
- Remote reading of disturbance recording and event log
- Self-diagnosis: Memories, output relays, A/D converters, auxiliary supply, cycles of execution of software, hardware failure
- Test of wiring, phase rotation and direction of the currents

Related equipment

- BA800 for ring CT 1500/1



The specifications and drawings given are subject to change and are not binding unless confirmed by our specialists.

